Interpreting One Concurrent Calculus in Another

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1. Introduction

It seems natural to use different languages for the different purposes of description or programming on the one hand, and prescription or specification on the other hand. Certainly there have been recent attempts to conflate these two types of language, but in the author's opinion they have not been convincing. It is, however, the purpose of this paper not to argue this point, but rather to explore a consequence of accepting the use of different languages for the two purposes.

I propose to use the word 'description' as a generalisation of 'program'; it is something which will describe both the spatial or modular structure of a performing agent (hardware or program) and also the temporal details of its performance. A prescription or specification, on the other hand, defines properties of the agent's performance - but only those properties which are expressible in terms of that part of the performance which is observable, e.g. the initial and final values of a program's memory, or the program's intermediate interactions with the user, or the electrical behaviour at the boundary of a chip. The connectives or operators for building specifications are naturally logical; many of those for building descriptions are not naturally logical but express operational or structural ideas like sequencing, interaction and juxtaposition.

If it is natural to use two languages, it is essential to define the relationship between them. It is not just that the designer (programmer, or describer) and the specifier should be able to interact, but that the two languages and what they express must form a single conceptual framework in which both designer and specifier operate (indeed, they may be the same person). We shall use the term calculus to mean a pair of languages in a definite relationship.

Having defined calculus, we then look at what it means to interpret one calculus in another. We have in mind that some calculi are primitive and general, but hard to apply in practice, while others are powerful and specific, designed for particular applications, and easier to work in. We therefore propose that it is useful to build an applied calculus on top of a basic one — i.e. interpret the former in the latter — to avoid an anarchic plethora of different calculi. The main result of the paper is that a particular applied calculus, namely a Hoare logic for an imperative concurrent programming language, may be

interpreted in the author's Calculus of Communicating Systems [5,7].

2. Calculi and their inter-relation

Definition A calculus is a triple

$$C = (A, \models, L)$$

where

- A is term algebra: terms built by a given set of operators;
- L is a logic: formulae built by a given set of connectives;
- |= ⊆ A× L is the satisfaction relation between terms and formulae.

This is a very bare definition, and leaves many options open. For example the interpretation of terms $t \in A$ may be given independently, or as an equivalence induced by \models as follows:

$$t_1 \equiv t_2$$
 iff, for all formulae $F \in \mathcal{L}, t_1 \models F$ iff $t_2 \models F$

Also, the satisfaction relation \models may be presented in different ways; either in terms of the model theory of A and \mathcal{L} , or proof-theoretically as an inference system whose sentences are of the form $t \models F$. In the latter case we shall call \mathcal{L} a proof calculus.

The notion of calculus is not so refined as the notion of institution of Goguen and Burstall [1]; in particular, we are not here concerned with variation of signature in a calculus, nor with their condition which requires the satisfaction relation to be preserved under signature-change. But the motivation for calculi is somewhat the same as for institutions. We are here mainly concerned with a single example of the relationship between two calculi; in studying calculi more generally we may well wish to enter the framework of [1], and the possibility of doing so must be investigated.

Our motivation for calculi is as follows. For different design purposes (designing programs in different languages, or designing hardware) different descriptive and prescriptive languages – i.e. different calculi – will be appropriate; but one will often wish to make use of the properties – e.g. satisfactions – of one calculus when working

in another. To this end, we have to set up relationships among calculi which will admit this transfer of properties between them.

Among many possible relationships, we wish to give an illustration of just two, with respect to specific calculi of interest in parallel computation.

Definition Let $C = (A, \models, L)$ and $C' = (A', \models', L')$ be two calculi.

We say h derives C' from C if h is a pair (h_1, h_2) of functions, $h_1 : A' \to A$ and $h_2 : \mathcal{L}' \to \mathcal{L}$, and $t \models F$ iff $h_1(t) \models h_2(F)$.

We say C' includes C if $A \subseteq A'$, $L \subseteq L'$ and $\models \subseteq \models'$. In this case we write $C \subseteq C'$.

The way we shall use these ideas is as follows. We take a simple basic calculus of processes,

$$PC = (PA, \models, PL)$$

We then take a simple but practical imperative programming language, presented as an algebra IA whose operators are the syntactic constructions of the language, and define its semantics by a semantic function $M_1:IA\to PA$. A natural Hoare logic which goes with IA is then expressed as the calculus

$$IC = (IA, \vdash, IL)$$

where IL is essentially a set of pairs of formulae of predicate logic, and \vdash expresses the inference rules of the Hoare logic. Thus IC is a proof calculus.

So far, we have the incomplete diagram

$$\begin{array}{ccc} PA & \models & PL \\ M_1 \uparrow & & & \\ IA & \vdash & IL \end{array}$$

We therefore seek a translation $M_2:IL\to PL$, to complete the diagram in a certain sense. Ignoring \vdash for a moment, we shall then have a calculus IC' derived by (M_1, M_2) from PC, i.e.

$$IC' = (IA, \models', IL)$$

where if $C \in IA$ and $F \in IL$ then $C \models' F$ is defined to mean $\mathcal{M}_1(C) \models \mathcal{M}_2(F)$. Since F is a pair (P,Q), we think of M as an interpretation of the Hoare sentences $P \parallel C \parallel Q$ in PC.

Finally, we find that $IC \subseteq IC'$, i.e. $\vdash \subseteq \models$. We propose that this is the correct way to formulate and to prove that a proof calculus is sound w.r.t. its interpretation in an underlying calculus.

3. The Process Calculus

Our process calculus

$$PC = (PA, \models, PL)$$

has been described at length elsewhere, and we shall only review it briefly here.

The process algebra PA consists of the terms of CCS in its pure form [6,7]. We start with a set $\mathcal{N}=\{a,b,c,\ldots\}$ of names, $\overline{\mathcal{N}}=\{\overline{a},\overline{b},\overline{c},\ldots\}$ of co-names, together forming the set $\mathcal{L}=\mathcal{N}\cup\overline{\mathcal{N}}$ of labels. These distinguish the ports at which communication occurs between agents; communication is always between a pair of ports with complementary labels, such as a and \overline{a} . We extend complementation to the whole of \mathcal{L} by setting $\overline{a}=a$. The labels also denote the actions occurring at ports. There is a special action τ ; it is the action performed by a composite agent when two of its component agents, running concurrently, interact with each other by performing a pair of complementary actions. We let α, β, \ldots range over $Act = \mathcal{L} \cup \{\tau\}$, the set of actions.

For agents, we first introduce a set PK of agent constants; we let A, B, \ldots range over PK. We let P, Q, \ldots range over PR, the set of agents, given by the following syntactic rules:

$$\begin{array}{lll} P & ::= & \alpha.P & \text{action prefix} \\ & \mid & \Sigma_{i \in I} P_i & \text{summation } (I \text{ an indexing set}) \\ & \mid & P_1 \mid P_2 & \text{composition} \\ & \mid & P \setminus L & \text{restriction } (L \subseteq \mathcal{L}) \\ & \mid & P[f] & \text{relabelling (where } f \text{ is a partial} \\ & & & \text{function on } \mathcal{L} \text{ and } f(\overline{\alpha}) = \overline{f(\alpha)}) \\ & \mid & A & \text{constant} \end{array}$$

We write 0 for the empty summation $\Sigma_{i\in\emptyset}P_i$.

We further require for each constant A a defining equation of the form

$$A \stackrel{\mathrm{def}}{=} P$$

For example, the definition

$$A \stackrel{\text{def}}{=} a.b.A + c.A$$

represents the agent which can repeatedly perform either the two actions a,b in sequence or the single action c. The behaviour of agents is defined as a labelled transition system with transition relations $\stackrel{\alpha}{\to}$ ($\alpha \in Act$), and the above agent is fully described by the transitions

$$A \xrightarrow{a} b.A, A \xrightarrow{c} A, b.A \xrightarrow{b} A$$

Space precludes a full definition of these relations, but we shall treat one further example which we shall need later. We wish to model the behaviour of a storage register which may hold an arbitrary natural number. Thus the constant REG_n (for each $n \geq 0$) represents the register in the state in which n is stored. In this state it may either be assigned a new content m, by performing the action a_m , or it may deliver up its content n by performing the action \overline{c}_m . The defining equations of the agents REG_n therefore take the form

$$REG_n \stackrel{\text{def}}{=} \Sigma_{m \geq 0} a_m . REG_m + \overline{c}_n . REG_n$$

Often we write such equations as a single parameteric equation

$$REG(x) \stackrel{\text{def}}{=} a(y).REG(y) + \overline{c}(x).REG(x)$$

using the convention that a positive label, here a, binds a value variable while a negative label, here c, can be parameterised by a value expression. Note that REG_n has the following transitions:

$$REG_n \xrightarrow{a_m} REG_m$$
 for each $m \ge 0$
 $REG_n \xrightarrow{\overline{c_n}} REG_n$

An agent \mathcal{P} interacting with the register, on the other hand, will perform an action labelled \overline{a}_m to assign a particular integer m to the register, and must be capable of performing any action $c_n, n \geq 0$, to read the contents of the register. If two agents P_1 and P_2 can both perform such actions (at various times in their histories) then the restricted composition

$$(P_1|P_2|REG_0)\setminus\{a,c\}$$

represents the system in which they, and (because of the restriction) only they, can make use of the register, perhaps competing for its attention.

Despite its simplicity, PA is a convenient vehicle for the expression and analysis of non-trivial parallel systems which are of practical importance. Many examples can be found in the author's forthcoming book [7].

Let us now turn to the component \mathcal{PL} of the calculus \mathcal{PC} ; the process logic. The only basic material from which the formulae of \mathcal{PL} are constructed is the set Act of actions. We let F, G, \ldots range over \mathcal{PL} , which is defined by the following syntactic rules:

$$F ::= \langle \alpha \rangle F$$
 progression $(\alpha \in Act)$
 $| \bigwedge_{i \in I} F_i$ conjunction $(I \text{ an indexing set})$
 $| \neg F$ negation

We write true for the empty conjunction $\bigwedge_{i\in\emptyset}F_i$. Intuitively, when we assert $\langle\alpha\rangle F$ of an agent P, we mean that P has a transition $P\stackrel{\Delta}{\to}P'$ such that F holds of the agent P'. Formally, the satisfaction relation \models which completes our calculus PC is defined as follows, by induction on the structure of formulae:

- 1. $P \models \langle \alpha \rangle F$ if, for some $P', P \stackrel{\alpha}{\rightarrow} P'$ and $P' \models F$
- 2. $P \models \bigwedge_{i \in I} F_i$ if, for all $i \in I$, $P \models F_i$
- 3. $P \models \neg F$ if it is not the case that $P \models F$

Now PL – like PA – is simple, but also powerful. With a few derived connectives, a wide range of properties of behaviour can be expressed very succinctly; for example, the ability or inability of a process to reach a deadlocked state is easy to express. Here are a few derived forms:

$$\begin{array}{lll} \langle s \rangle & \text{means} & \langle \alpha_1 \rangle \langle \alpha_2 \rangle \cdots \langle \alpha_n \rangle F & (s = \alpha_1 \cdots \alpha_n) \\ [s] F & \text{means} & \neg \langle s \rangle \neg F \\ \bigvee_{i \in I} F & \text{means} & \neg \bigwedge_{i \in I} \neg F \end{array}$$

As an example, let us suppose that we wish to express the property of REG (above) that, whatever actions it performs, it can always yield some natural number as its content. Then the following formula F expresses the property, where Nat is the set of natural numbers:

$$F \equiv \bigwedge_{s \in Act} [s] \bigvee_{m \in Net} \langle c_m \rangle true$$

Moreover, it is easy to establish that, for each $n \in Nat$,

$$REG_n \models F$$

Now PL can be used to induce congruences upon the term algebra PA, and by dividing PA by any such congruence one obtains an interesting and rich algebraic theory. The simplest congruence is known as strong congruence and denoted by \sim ; it is defined according to the general recipe mentioned directly after the definition of calculus in Section 2, namely:

$$P \sim Q$$
 if, for all $F \in \mathcal{PL}$, $P \models F$ iff $Q \models F$

The algebraic properties of this congruence, and others, can be found in [7]. It is worth noting that these congruences have other characterisations independent of $P\mathcal{L}$, and this gives them more objective status. We need not pursue this matter further here; we have now treated $P\mathcal{C}$ enough for our present purpose, namely the interpretation in $P\mathcal{C}$ of the imperative calculus $I\mathcal{C}$, to which we now turn.

4. The Imperative Calculus

As announced earlier, our imperative calculus

$$IC = (IA, \vdash, IL)$$

is, in essence, the Hoare logic of a simple imperative programming language. As basic sets we take X, the program variables, and \mathcal{F} , the function symbols (each function symbol having an arity ≥ 0). We let X and F range over X and F respectively. We also let E range over the expressions \mathcal{E} , and C range over the commands C, defined by the following syntactic rules:

$$E ::= X \qquad \text{variable} \\ \mid F(E_1, \dots, E_n) \qquad \text{function application} \\ C ::= X := E \qquad \text{assignment} \\ \mid C : C' \qquad \text{sequential composition} \\ \mid \text{if } E \text{ then } C \text{ else } C' \text{ conditional} \\ \mid \text{while } E \text{ do } C \qquad \text{iteration} \\ \mid \text{local } X \text{ in } C \text{ end} \qquad \text{local variable} \\ \mid C \text{ par } C' \qquad \text{parallel composition} \\ \mid \text{skip} \qquad \text{no action}$$

(Note that constants like 0.1,... and arithmetic operations like +,-,... are function symbols with arity zero and

arity two respectively, and we would write X+1 in place of +(X,1()).)

Thus the imperative algebra IA is a term algebra with two sorts (expressions and commands) and with the syntactic constructions as operators. These constructions are well enough known to need little description. Suffice it to say that the local variable construction gives scope C to the variable X, and that in the parallel composition construction C and C' are supposed to run in parallel, communicating through variables to which they both share access.

Now Hoare's original logic [3] for partial correctness of sequential programs employed sentences of the form

$$P\{|C\}|Q$$

whose intended meaning is "if C is executed starting in a state satisfying P, then its terminating state (if any) will satisfy Q". P and Q are normally taken to be formulae of first order logic, containing free occurrences of the program variables. A natural rule of inference is then the following rule for sequential imposition:

$$\frac{P \|C_1\|Q \qquad \qquad Q \|C_2\|R}{P \|C_1;C_2\|R}$$

In fact, as is well known, Hoare and others have given sets of inference rules for various sequential languages. If we were only concerned with sequential programs, without par, then we would define the *imperative logic* I to have pairs (P,Q) as its formulae (where P,Q are formulae of predicate logic), and we would take $P \{C\}Q$ to be a way of writing $C \vdash (P,Q)$. Then we would complete the imperative proof calculus IC by defining the relation \vdash as the set of pairs (C,(P,Q)) such that $P\{C\}Q$ is provable in the appropriate Hoare logic.

In the presence of par things are not so easy, because without some constraint upon the language there is no natural inference rule corresponding to par. However, as Owicki and Gries showed [8], there is a natural rule if we impose the following condition:

In any command of the form C_1 par C_2 , C_1 may not assign to any program variable which occurs free in C_2 , and conversely.

We shall proceed to formulate $I\mathcal{L}$ and \vdash with this in mind. First, we shall decorate each Hoare sentence with two disjoint sets \tilde{X} and \tilde{Y} of program variables, as follows:

$$P\{C\}Q\}_{\nu}^{X}$$

We shall require that \tilde{Y} contains all the variables free in C to which C makes any assignment, and \tilde{X} contains all other variables free in C; also, that $\tilde{X} \cup \tilde{Y}$ contains all the program variables free in P and Q. If these conditions are all satisfied then we say the sentence is admissible. Now the rule for sequential compositions becomes the following:

$$\frac{P\{\!\!\{C_1\}\!\!\}Q\mid_{\tilde{Y}_1}^{\tilde{X}_1} \qquad Q\{\!\!\}C_2\}\!\!\}R\mid_{\tilde{Y}_2}^{\tilde{X}_2}}{P\{\!\!\{C_1\!\!\}\!\!\}C_1\!\!\}P\mid_{\tilde{Y}_1\cup\tilde{Y}_2}^{\tilde{X}_1}\!\!)\cup(\tilde{X}_2-\tilde{Y}_1)}$$

where it may easily be checked that the conclusion is admissible provided that the hypotheses are so. For parallel composition, we impose a side condition on \tilde{X}_1 , \tilde{X}_2 , \tilde{Y}_1 and \tilde{Y}_2 which ensures the above stated condition on C_1 and C_2 , assuming that the hypotheses are admissible:

$$\frac{P_1 \{\!\!\{ C_1 \}\!\!\} Q_1 \mid_{\tilde{Y}_1}^{\tilde{X}_1} \qquad P_2 \{\!\!\{ C_2 \}\!\!\} Q_2 \mid_{\tilde{Y}_2}^{\tilde{X}_2}}{(P_1 \wedge P_2) \{\!\!\{ C_1 \text{ par } C_2 \}\!\!\} (Q_1 \wedge Q_2) \mid_{\tilde{Y}_1 \cup \tilde{Y}_2}^{\tilde{X}_1 \cup \tilde{X}_2}}$$

provided that $\tilde{X_1} \cap \tilde{Y_2} = \tilde{Y_1} \cap \tilde{X_2} = \tilde{Y_1} \cap \tilde{Y_2} = \emptyset$. Note that under these conditions the conclusion will also be admissible. It is rather easy to complete the Hoare logic by supplying inference rules for the other constructions of IA, and we shall take them for granted.

We therefore modify our definition of $I\mathcal{L}$, the imperative logic; it consists of quadruples $(P,Q,\tilde{X},\tilde{Y})$ and we take $P\{\!\!\{C\}\!\!\}Q \mid_{\tilde{Y}}^{\tilde{X}}$ to be a way of writing $C \vdash (P,Q,\tilde{X},\tilde{Y})$. Then we complete IC by defining \vdash as the set of pairs $(C,(P,Q,\tilde{X},\tilde{Y}))$ such that $P\{\!\!\{C\}\!\!\}Q \mid_{\tilde{Y}}^{\tilde{X}}$ is admissible, and provable in the Hoare logic.

Much has been written about the soundness and (relative) completeness of various Hoare logics. We do not address the problem of completeness in this paper; however, the soundness of the imperative calculus is the subject of the following section.

5. Interpreting the Imperative Calculus

Let us review what we mean by the soundness of IC w.r.t. its interpretation in PC. First, we have to express the interpretation as a pair of translations

$$M_1:IA \rightarrow PA$$
, $M_2:IL \rightarrow PL$

Then we have to show that, for any $C \in IA$ and any $(P,Q,\tilde{X},\tilde{Y}) \in PA$,

$$C \vdash (P, Q, \tilde{X}, \tilde{Y})$$
 implies $M_1(C) \models M_2(P, Q, \tilde{X}, \tilde{Y})$.

In this section, we outline the translations M_1 and M_2 , and also outline the proof of soundness.

The translation M_1 from imperative programs to CCS agents rests upon the simple idea that each program variable X corresponds to a relabelled version of the register agent defined in Section 3 above, i.e.

$$REG_X(x) \stackrel{\text{def}}{=} a_X(y).REG_X(y) + \overline{c}_X(x).REG_X(x)$$

Moreover, the translation $M_1(C)$ of any command C, in which the program variable X occurs free, will be an agent capable of performing actions \overline{a}_X (to assign to X) and actions c_X (to obtain the contents of X). It is particularly important to realise that no assumption is made,

in defining M_1 , that a program C will have exclusive access to the variables which it uses. Thus, for example, the translation $M_1(Y:=X+X)$ will have many possible execution sequences; it can perform the sequence

$$\overline{c}_{X}(6)$$
 $\overline{c}_{X}(6)$ $a_{Y}(12)$

which is what it will do if the variable X contains the value 6 unchanged throughout the execution of Y:=X+X; but alternatively it can perform the sequence

$$\overline{c}_{\chi}(6)$$
 $\overline{c}_{\chi}(7)$ $a_{\gamma}(13)$

which is what it will do if some other agent increments the value of X between the two readings of that variable.

The full translation is given in [5,7]; here we need only give its flavour by indicating how it treats local variables. The local variable construction

$$C' = local X in C end$$

has two important effects. First, it dedicates the variable X to C, ensuring that no other agent can access X; second, it ensures that any \overline{a}_X or c_X actions which occur in the behaviour of C (representing the writing and reading of X by C) are replaced by τ actions in the behaviour of C'. These are both achieved by the simple definition

$$M_1(\text{local }X \text{ in }C \text{ end}) = (\text{Reg}_X(0) \mid M_1(C)) \setminus \{a_X, c_X\}$$

(where we assume X is initially given the value 0).

The remainder of the definition of M_1 is not hard, but need not concern us here. It has the pleasant property that in the theory of PA, divided by one of the congruences mentioned at the end of Section 3 above, one can easily prove many familiar equational laws for the transformation of programs. Indeed, a principle motive for investigating M_1 was to obtain those laws as a justification for the algebraic theory PA.

We now turn to defining $M_2:IL\to PL$. That is, we look for a uniform construction of a modal formula F from a quadruple P,Q,\tilde{X},\tilde{Y} such that $C\models F$ asserts, of C, the following:

Let m, and m' be two valuations of the variables $\tilde{X} \cup \tilde{Y}$, and let s be a terminating action sequence of C which can lead from initial valuation m to final valuation m' assuming no external interference with the variables $\tilde{X} \cup \tilde{Y}$. Then if m satisfies P, m' satisfies Q.

Now let us write $\tilde{Z} = \tilde{X} \cup \tilde{Y}$, and let us write Dom(m) for the set of variables for which the valuation m is defined. Furthermore, let us denote by $m \|s\| m'$ the property that the s is a terminating action sequence, and could consistently lead from initial valuation m to final valuation m' without external interference (this property is quite easy to define inductively on s). Let us write $P\{m(\tilde{Z})/\tilde{Z}\}$ for the formula obtained by replacing in P the variables \tilde{Z} by their values in m. Then the formula $M_2(P,Q,\tilde{X},\tilde{Y})$ may be written as a mixture of predicate and modal logic as follows:

$$\forall m, m', s.$$
 $(Dom(m) = Dom(m') = \tilde{Z} \land m\{s\}m' \land (s) \text{true} \land P\{m(\tilde{Z})/\tilde{Z}\})$
 $\supset Q\{m'(\tilde{Z})/\tilde{Z}\}$

Now we first assert that this formula can be encoded entirely in $P\mathcal{L}$. This may seem surprising, but the power of infinite conjunction in $P\mathcal{L}$, with arbitrary indexing sets, is what makes it possible. Second, we assert that if $P\{|C\}, Q | \frac{X}{Y}$ is interpreted as $M_1(C) \models M_2(P, Q, \tilde{X}, \tilde{Y})$ then the rule for parallel composition in Section 4, and indeed all the other rules of the Hoare logic described there, are sound. (In this proof, the side condition on the rule for par is indeed crucial.) Therefore everything that is provable by these rules is true in the interpretation in PC, and we have demonstrated the soundness of the imperative calculus w.r.t. the underlying process calculus, as we intended.

6. Conclusion

In this paper we have shown how one calculus can be interpreted in another, more basic, calculus. The particular example we chose was to interpret an imperative programming calculus – likely to be more familiar to applications specialists – in the basic process calculus CCS. This interpretation was rather easy and natural, and lends weight to CCS as a foundation for calculi which are more oriented to particular applications; one hopes that CCS can similarly support many applied calculi.

Indeed there is a calculus, based upon the same imperative programming language IA, which presents an immediate challenge of the above kind. For our proof calculus IC is quite restrictive; the domain of its satisfaction relation \vdash is confined to programs in which the parallel construction C_1 par C_2 is only admitted when C_1 assigns to no variable occurring free in C_2 and vice versa. This condition ensures that programs are deterministic, but it is an unnecessarily strong condition to impose for this purpose. There are interesting deterministic programs in IA which do not satisfy the condition; indeed, there are useful non-deterministic programs which are intuitively natural and which one would like to analyse in a richer calculus than IC.

Such richer calculi exist, for the same imperative programming language IA. One good example stems from the work of Jones [4]; in effect, he replaces Hoare sentences $P\{C\}Q$ by richer sentences $(P,R)\{C\}(Q,S)$, where P and Q are pre- and post-conditions as before, while R is a condition upon whose truth C will rely before every step of its execution, and S is a condition whose truth C will, in turn, guarantee after every step of its execution. Now Jones places no restriction upon the parallel construction C_1 par C_2 , but will only allow a Hoare sentence about C_1 par C_2 to be inferred from Hoare sentences about C_1 and C_2 whose rely and guarantee conditions complement

one another suitably. Stirling [9] has formulated the appropriate Hoare logic explicitly, as a generalisation of the Owicki-Gries system, and has proved it sound w.r.t. an independently given operational semantics. To justify PC as a good foundation, it is therefore important to formulate Stirling's Hoare logic as a calculus in our sense, and interpret it in PC just as we have interpreted IC in PC.

Hitherto we have concentrated upon Hoare logics of partial correctness: logics which assert nothing about program termination. There are logics of total correctness for the same programming language IA, for example the weakest pre-condition logic of Dijkstra. It appears that our process logic PL does not express liveness or eventuality properties strongly enough for PC to support an interpretation of a logic of total correctness. However, there are stronger process logics than PL which do express eventuality – Hennessy and Stirling [2] proposed one – and we would like to interpret a total correctness calculus for IA in a correspondingly stronger process calculus.

We hope to have shown that the notions of calculus, and of interpreting one calculus in another, are fruitful and unifying.

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