

Concurrent Logic/Constraint Programming: The Next 10 Years

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Two Approaches to Addressing Novel Applications

- ◆ Synthetic
 - More expressive power
 - Integration of features
- ◆ Analytic
 - Identifying smaller fragments of LP with nice and useful properties
cf. Turing machines vs. pushdown automata
 - Separation prior to integration

Grand Challenges

- ◆ A “ λ -calculus” in concurrency field
cf. X -calculus (calculus of X)
 X : CS, pi, action, join, gamma, ambient, . . .
- ◆ Common platform for non-conventional computations (parallel, distributed, embedded, real-time, mobile, . . .)
- ◆ Type systems (in the broadest sense) and frameworks of analysis for both logical and physical properties

LP vs. Concurrent LP

- ◆ Concurrent LP = LP + committed choice
= LP – completeness

???

Choice is essential for specifying arbitration, changes denotational semantics drastically, but otherwise . . .

LP vs. Concurrent LP

- ◆ Concurrent LP
 - = LP + directionality (of dataflow)
 - = Logic + embedded concurrency control
- ◆ **Moded** Concurrent LP / CCP:
 - ask + tell + strong moding
- ◆ Can/should share more interest with (I)LP

Example: Parallel/Network Programming

- ◆ Parallel and distributed computing are the difficult areas where we need good models and methodologies to build large applications quickly.
- ◆ A good chance for us to demonstrate the power of simple and “usable” languages with an appropriate level of abstraction.
 - should be simple and accessible to network programmers; otherwise Java will do!

Example: Parallel/Network Programming

- ◆ Still done with “classical” constructs
 - mutex, serialization, monitors, . . .
 - cf. Obliq, Java, . . .
- ◆ . . . or with APIs (cf. MPI)
- ◆ Suffering from low-level details
 - e.g., Unix sockets
- ◆ Far from being “provably correct”

Example: Network Applications Need to Deal with:

- ◆ Physical locations (nodes, sites)
- ◆ Resources
 - space (heap usage)
 - time and stack usage
- ◆ Security
 - high-level: safety of comm. protocols etc.
 - low-level: leave to Java’s bytecode verifier?
- ◆ Transmission of various entities
- ◆ Various patterns of communication

GHC and KL1: Brief History

(cf. CACM March 1993 issue)

- ◆ 1983 Concurrent Prolog, PARLOG
- ◆ 1983-84 big controversy (in ICOT) on LP vs. concurrent LP for parallel KIP systems
- ◆ 1984 Guarded Horn Clauses designed
- ◆ 1985 first paper (ICOT TR103, LNCS 221)
- ◆ 1985 GHC-to-Prolog compiler (SLP'85)
- ◆ 1985-86 subsetting to Flat GHC
- ◆ 1986 Prolog-to-GHC compiler (ICLP'86)

Brief History (cont'd)

- ◆ 1988 Strand (\rightarrow PCN \rightarrow CC++)
- ◆ 1988(?) PIMOS operating system
- ◆ 1988 unfold/fold transformation and transaction-based semantics (FGCS'88)
- ◆ 1989 Concurrent Constraint Programming (Saraswat)
- ◆ 1989 atomic vs. eventual tell discussed
- ◆ 1989 message-oriented impl. (LPC'89)

Brief History (cont'd)

- ◆ 1987 MRB (1-bit RC) scheme (ICLP'87)
- ◆ 1987 // impl. of Flat GHC on Multi-PSI v1 (6 PEs, ICLP'87)
- ◆ 1987 book on GHC (in Japanese)
- ◆ 1987 ALPS (Maher, ICLP'87)
- ◆ 1987-1988 KL1 (with *shoen*, vectors, MRB)
- ◆ 1988 // impl. of KL1 on Multi-PSI v2 (64 PEs, FGCS'88, ICLP'89)

Brief History (cont'd)

- ◆ 1990 Moded Flat GHC and constraint-based analysis (ICLP'90)
- ◆ 1990(?) MGTP-on-KL1 project started
- ◆ 1990 first structural OS (InfoJapan'90)
- ◆ 1990 Janus (NACLCP'90)
- ◆ 1990 Computer J. paper on GHC + KL1
- ◆ 1991 denotational semantics of CCP (POPL'91)

Brief History (cont'd)

- ◆ 1991 AKL (\rightarrow Oz \rightarrow Oz2 \rightarrow Oz3) (ILPS'91)
- ◆ 1992 // impl. of KL1 on PIM/m and PIM/p (FGCS'92)
- ◆ 1992 various parallel applications written in KL1 including OS, biology, CAD, NL, law, automated deduction, . . .
- ◆ 1992 message-oriented // impl. of Moded Flat GHC on SMP (FGCS'92)

Brief History (cont'd)

- ◆ 1995 constraint-based mode systems in practice (ICLP'95, PSLs'95)
- ◆ 1996 klint v1 (mode analyzer for/in KL1)
- ◆ 1996 constraint-based error diagnosis, theory and practice (JICSLP'96)
- ◆ 1997 kima v1 (diagnoser) based on klint
- ◆ 1997 constraint-based error correction

Brief History (cont'd)

- ◆ 1992 KLIC (KL1-to-C compiler) desinged (KL1 without *shoen* or MRB)
- ◆ 1992 MGTP solved an open problem (IJCAI'93 award)
- ◆ 1994 proof system for CCP (POPL'94)
- ◆ 1994 KLIC paper (PLILP'94)
- ◆ 1994 Moded Flat GHC in detail (NGC)
- ◆ 1994 Toontalk (ICLP'95)

Brief History (cont'd)

- ◆ 1998 klint v2 with linearity (static MRB) & type analysis
- ◆ 1998 NSTO analysis for Moded Flat GHC

Guarded Horn Clauses and KL1

- ◆ Weakest Concurrent Constraint Language
 - ask + eventual tell (asynchronous)
 - parallel composition
 - hiding
 - nondeterministic choice
- ◆ A realistic language as well as a model
 - value passing
 - data structures (cf. CCS, CSP, . . .)

Logical Variables as Communication Channels

- ◆ Data- and demand-driven communication
- ◆ Messages with reply boxes
- ◆ First-class channels (encoded as lists or difference lists)
- ◆ Replicable read-only data
- ◆ Implicit redirection across sites

Guarded Horn Clauses and KL1

- ◆ Evolving process structures (since 1985)
- ◆ Physical locations (KL1)
- ◆ Object identity (by logical variables)
- ◆ I/O completely within the basic framework
- ◆ Read/write capabilities (with strong moding)
- ◆ Resource-conscious programming (with linearity)
- ◆ Scope extrusion (“method calls” encoded as messages)

Guarded Horn Clauses as CCP

- ◆ “. . . it is quite natural to view a GHC program in terms of binding information and the agents that observe and generate it.”
- ◆ “In general, a goal can be viewed as a process that observes input bindings and generates output bindings according to them. Observation and generation of bindings are the basis of computation and communication in our model.” — *ICOT TR-208 (1986)*

GHC after 13 years

- ◆ The simplest fragment of CCP turned out to be surprisingly versatile, after heated discussions and programming experiences.
- ◆ As conjectured in 1985 (LNCS 221), GHC as the weakest fragment of CCP has been (d)evolving by featuring static constructs.
 - static constructs added: mode systems
 - operational constructs added: @node() and priorities

GHC after 13 years

- ◆ Yet to see what additional features are really necessary, and why
 - Example: higher-order constructs
 - “design pattern” programming
 - object encoding
- ◆ Pure CCP or impure CCP?
 - cf. Oz approach (ports, cells, higher-order, etc.)

GHC after 13 years

- ◆ Strong moding (1990, ICLP) ensures some aspects of security by assigning a capability/polarity to each variable occurrence and each position of data structures.
 - write capability can't be duplicated or discarded
 - read, non-linear capability can be duplicated
 - linearity avoids distributed GC
 - unification (constraint solving) degenerates to assignment

Working Example of Network Applications

- ◆ 1996 KLIC Programming Contest
 - KLIC = KL1 (GHC) implementation on Unix (<http://www.icot.or.jp>)
 - Submitted programs included
 - Web server totally written in KL1, and
 - Web browser with most features.
 - Call for Participation: 1998 KLIC Programming Contest (<http://www.icot.or.jp>)

Some Failures and Problems

- ◆ Misleading names
 - Concurrent LP: Sounds like an incomplete variant of LP (worse: committed-choice LP)
 - CCP: Liable to forget its prehistory (<1987)
Concurrent LP is CCP.
- ◆ Can very easily be forgotten by LP, concurrency and constraint communities

Some Failures and Problems

- ◆ Good textbooks and tutorial materials yet to be published
- ◆ Few research groups (except semantics)
 - Oz (DFKI + SICS + . . .)
 - GHC/KLIC (AITEC = former ICOT)
 - many people “graduated” too early

Some Failures and Problems

- ◆ Shortage of communication with neighboring communities (functional, OO, . . .)
 - e.g., declarative arrays, program analysis
- ◆ Simple and general, but looks a bit too abstract — idioms should be encoded (cf. objects, messages, channels, . . .).

Challenges to share with proponents of other declarative paradigms

- ◆ How can we program XXX in our formalisms?
 - Dynamic data structures (e.g., cyclic graphs)
 - MUD and virtual reality
 - Teleconferencing
 - Forms
 - Live Access Counters
 - . . .

LP and Concurrent LP/CCP

- ◆ Targetted (currently) at different levels:
 - LP: KR, reasoning, search, etc.
 - Concurrent LP: simple model for concurrency and communication
 - CCP: unified model for reactive systems and infrastructures for reactive agents
 - Should be very carefully ‘integrated’
- ◆ However, they still have much in common and can benefit from each other!

Conclusions (2)

- ◆ Constraint-based static systems can make CCP a simple, powerful, and safe language for
 - parallel computing,
 - distributed computing,
 - real-time computing, and
 - high-performance computing,and give us strong support for programming.
cf. untyped vs. typed λ -calculus

Conclusions (1)

- ◆ CCP without static systems has been a simple and elegant formalism of concurrency, . . .
. . . and at the same time it has been a stable, full-fledged programming language.
 - cf. other formalisms of concurrency

PART II

Potentialities of Constraint-Based Program Analysis

Can a machine debug your program?

```
append([ ], Y,Z ) :- true | Y=Z.  
append([A|Y],Y,Z0) :- true |  
                        Z0=[A|Z], append(X,Y,Z).
```

- ◆ “>90% correct”
- ◆ cf. Ill-formed sentences in NL processing

Can a machine debug your program without specifications?

```
append([ ], Y,Z ) :- true | Y=Z.  
append([A|Y],Y,Z0) :- true |  
                        Z0=[A|Z], append(X,Y,Z).
```

- ◆ Mode analyzer suspects that *X* is *the* reason.
- ◆ The problem can be fixed by replacing *X* or making *X* have more occurrences.
- ◆ The debugger searches well-moded mutations. Typing doesn't help in this case.

Can a machine debug your program without specifications?

```
append([ ], Y,Z ) :- true | Y=Z.  
append([A|Y],Y,Z0) :- true |  
                        Z0=[A|Z], append(X,Y,Z).
```

- ◆ Non-well-moded, under the assumption of “cooperative communication.”
- ◆ Mode analyzer finds a minimal inconsistent set of mode constraints, which suspects *X* in the recursive call and the first *Y* in the head.

Can a machine debug your program without specifications?

```
append([ ], Y,Z ) :- true | Y=Z.  
append([A|Y],Y,Z0) :- true |  
                        Z0=[A|Z], append(X,Y,Z).
```

- ◆ The debugger finds 6 alternatives, but prefers ‘generic’ programs and propose:
append([A|X],Y,Z0) :- true |
 Z0=[A|Z], append(X,Y,Z).
- ◆ We are happy if the system proposes the intended program and nothing else . . .

Can a machine debug your program without specifications?

```
append([ ], Y,Z ) :- true | Y=Z.  
append([A|Y],Y,Z0) :- true |  
                        Z0=[A|Z], append(X,Y,Z).
```

. . . but it proposes one more alternative:

```
append([A|Y],X,Z0) :- true |  
                        Z0=[A|Z], append(X,Y,Z).
```

- ◆ Fine, it's not `append` but does something meaningful (unlike many other junks)!

References

- ◆ Cho, K. and Ueda, K.:
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- ◆ Ueda, K., Ajiro, Y. and Cho, K.:
Error-correcting Source Code (submitted to CP'98)